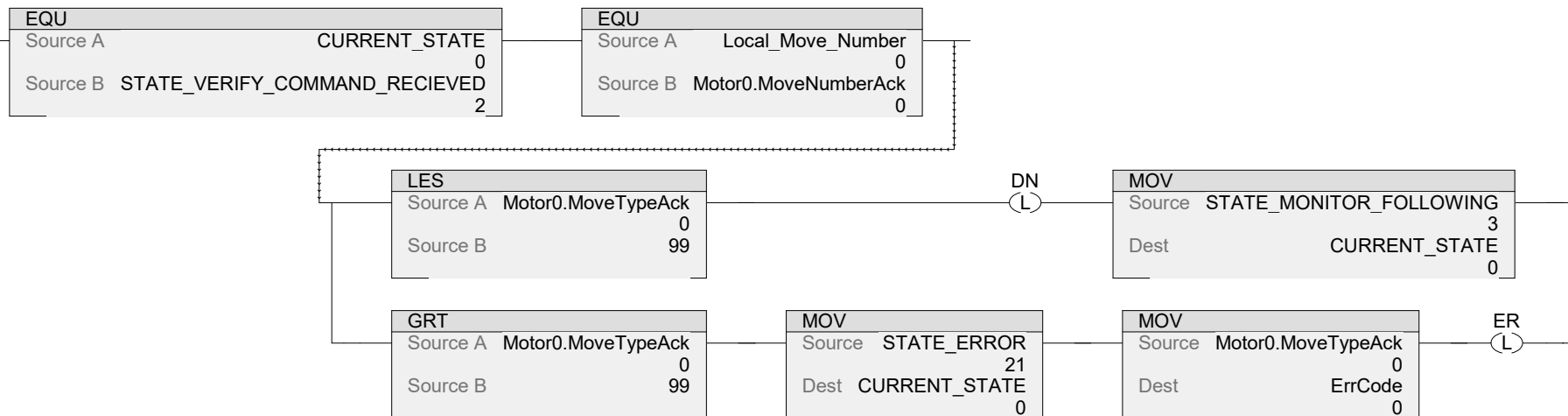


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VERIFY MOVE RECIEVED

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Monitor the move number ack and wait for it to equal the move number used to start following. This will indicate the motor has received the command. Once it has been verified that the motor has received the command, check the move type ack to confirm it was accepted. If the motor is unable to configure the slave axis to start following the master axis, it will return a move type error (MoveTypeAck greater than 99). If a move type error has occurred, set the error code equal to the move type error.



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CHECK FOR INTERRUPTIONS

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Monitor conditions that would indicate the slave axis is no longer following the master or that the following parameters may have been changed. If the move number set by this routine is modified or the move number ack is changed after following has been started, transition to the move done state to indicate that the motor may no longer be following the master axis with the parameters set in this routine.

